



Characterizing classical minimal surfaces via the entropy differential

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ABSTRACT. We introduce on any smooth oriented minimal surface in Euclidean 3-space a meromorphic quadratic differential, P , which we call the entropy differential. This differential arises naturally in a number of different contexts. Of particular interest is the realization of its real part as a conservation law for a natural geometric functional – which is, essentially, the entropy of the Gauss curvature. We characterize several classical surfaces – including Enneper’s surface, the catenoid and the helicoid – in terms of P . As an application, we prove a novel curvature estimate for embedded minimal surfaces with small entropy differential and an associated compactness theorem.

1. Introduction

Let $\Sigma \subset \mathbb{R}^3$ be a smooth, oriented minimal surface. In this paper, we introduce a meromorphic quadratic differential P on Σ , which we call the *entropy differential*. We use P to characterize several classical surfaces – including Enneper’s surface, the catenoid and the helicoid. In particular, subsets of Enneper’s surface are the only minimal surfaces on which P vanishes – a fact which we use to prove a novel curvature estimate for embedded minimal surfaces with small entropy differential and an associated compactness result.

The differential P arises naturally in a number of different contexts. Of particular interest is the realization of $T = \operatorname{Re} P$, which we call the *entropy form*, as a conservation law for the diffeomorphism invariant functional

$$\mathcal{E}[g] = \int_{\Sigma} K_g \log K_g \mu_g.$$

This functional, which is a type of entropy for the curvature, has been previously considered by R. Hamilton in the context of the Ricci flow on surfaces [14]. In particular, we show that if g is a minimal surface metric (i.e. the metric induced by a smooth minimal immersion) for which $K_g \neq 0$, then the metric $\hat{g} = (-K_g)^{3/4} g$ is a critical point of \mathcal{E} with respect to compactly supported conformal deformations. The crucial fact used here is the observation – due to Ricci [22] – that such minimal surface metrics satisfy the so-called *Ricci condition*:

$$\Delta_g \log |K_g| = 4K_g.$$

The differential P also arises as a certain geometric Schwarzian derivative of the Gauss map – a point of view which has antecedents in [9, 12] – and which we will study more thoroughly in a forthcoming paper [3].

A key observation of the present paper is that, modulo rigid motions, a minimal surface is determined, up to a three-parameter family, by its Hopf differential Q and its entropy differential P . This allows one to characterize several classical minimal surfaces in terms of simple relationships between the Hopf and entropy differentials:

Theorem 4.1. *Let Σ be a smooth oriented non-flat minimal surface in \mathbb{R}^3 with entropy differential P . We have:*

- (1) *If $P \equiv 0$, then up to a rigid motion and homothety, Σ is contained in Enneper’s surface;*
- (2) *If $\lambda \neq 0$ and $P \equiv \lambda Q$, then, up to a rigid motion and homothety, Σ is contained in a surface $C \in \mathcal{C}$. If Σ is properly embedded, then it is the catenoid;*
- (3) *If $\lambda \neq 0$ and $P \equiv i\lambda Q$, then, up to a rigid motion and homothety, Σ is contained in a surface $H \in \mathcal{H}$. If Σ is properly embedded, then it is the helicoid.*

The families \mathcal{C} and \mathcal{H} are, respectively, the *deformed catenoids* and *deformed helicoids*. These are one parameter families of surfaces containing, respectively, the catenoid and the helicoid – their geometry is discussed thoroughly in Section 4.

A consequence of Item (1) of Theorem 4.1 are a family of novel curvature estimates for embedded minimal surfaces. Namely, we introduce a certain family of scale invariant quantities which measure the size of the entropy form and use standard blow-up arguments to derive curvature bounds for embedded surfaces for which these quantities are small. Specifically, for a constant $\alpha > 0$ and smooth minimal surface Σ with entropy form T , we define:

$$||T||_{\Sigma, \alpha} := 2^{\frac{1}{2(1+\alpha)}} \int_{\Sigma} |T|_g^{\frac{1}{1+\alpha}} |K_g|^{\frac{\alpha}{\alpha+1}} \mu_g.$$

We justify this family by noting that, on the one hand they are scale invariant and, on the other, the “endpoints” are very natural. Indeed,

$$\lim_{\alpha \rightarrow \infty} ||T||_{\Sigma, \alpha} = \int_{\Sigma} |K_g| \mu_g,$$

i.e., one endpoint is the total Gauss curvature, a well studied quantity in minimal surface theory. While,

$$\lim_{\alpha \rightarrow 0} ||T||_{\Sigma, \alpha} = \sqrt{2} \int_{\Sigma} |T|_g \mu_g,$$

i.e., the other endpoint is the L^1 norm of the entropy form which is invariant under the standard action of $\mathrm{PSL}(2, \mathbb{C})$ on the Gauss map of Σ , see [3]. We will not deal directly with this quantity due to the fact that the presence of umbilic points tends to make it infinite.

As these quantities are scale invariant, standard blow-up arguments give the following curvature estimates:

Theorem 5.3. *Given $\alpha > 0$, there exist constants $\epsilon = \epsilon(\alpha) > 0$ and $C = C(\alpha) > 0$ so that: if Σ is a properly embedded minimal surface in B_{2R} and*

$$\|T\|_{\Sigma, \alpha} < \epsilon,$$

then

$$R^2 \sup_{B_R \cap \Sigma} |A|^2 \leq C^2.$$

In [Section 5.2](#), we address the question of the best possible ϵ and some partial results are obtained. In particular, we obtain the following identity:

Corollary 5.10. *Let Σ be a non-flat properly immersed minimal surface in \mathbb{R}^3 of finite total Gauss curvature with genus g and e embedded ends, then*

$$\lim_{\alpha \rightarrow 0} \alpha \|T\|_{\Sigma, \alpha} = \frac{\pi}{4} \left(8 + 12g + 10(e - 2) + \sum_{p \in \mathcal{E} \cup \mathcal{U}} \frac{n(p)}{n(p) + 1} \right).$$

Here \mathcal{E} is the set of ends and $n(p) \geq 0$ for $p \in \mathcal{E}$ is the order of branching of the end, i.e., the order of branching of the extension of the Gauss map to p , while \mathcal{U} is the set of umbilic points and $n(p) \geq 1$ is the order of the umbilic point for $p \in \mathcal{U}$.

This suggests that as $\alpha \rightarrow 0$

$$\epsilon(\alpha) = \frac{2\pi}{\alpha} + o\left(\frac{1}{\alpha}\right).$$

which would be sharp on the catenoid. Using standard techniques, we observe that our curvature estimate gives a corresponding compactness results which we record in [Theorem 5.13](#). We conclude the paper with [Section A](#), wherein the entropy form is used to make a connection between minimal surfaces in \mathbb{R}^3 and gradient Ricci soliton metrics on surfaces.

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2. A Geometric Entropy Functional for Surfaces

2.1. Definitions

We assume \mathbb{R}^3 to be equipped with the standard Euclidean metric g_E and orientation. Let $B_R(p)$ be the open Euclidean ball in \mathbb{R}^3 with radius $R > 0$

and center p . If p is omitted then the ball is assumed to be centered at the origin in \mathbb{R}^3 . Let M be an open orientable smooth 2-manifold. For a smooth immersion $\mathbf{x} : M \rightarrow \mathbb{R}^3$ let $\Sigma = \mathbf{x}(M)$, we say Σ is properly embedded if \mathbf{x} is proper and injective. Moreover, let $g = \mathbf{x}^*g_E$ be the first fundamental form. We write ${}^g\nabla$ for the Levi-Civita connection, K_g for the Gauss curvature, and μ_g for the area form of g . The integrable almost complex structure on M induced by g and the orientation will be denoted by J . Furthermore, for $A \in \Gamma(S^2(T^*M))$, we define $(JA)(X, Y) = A(JX, Y)$ where $X, Y \in \Gamma(TM)$ are smooth vector fields on M . Here, as usual, $S^2(T^*M)$ denotes the second symmetric power of the cotangent bundle of M . In particular, the map $A \mapsto A + iJA$ embeds the space of symmetric trace-free 2-forms on M into the space of quadratic differentials on M . Furthermore, we use the standard fact that $A + iJA$ is holomorphic if and only if A is divergence-free.

Let \mathbf{n} denote the orientation compatible Gauss map of \mathbf{x} taking values in ∂B_1 , the unit-sphere in \mathbb{R}^3 centered at 0. The second fundamental form of \mathbf{x} will be denoted by A and its trace with respect to g , the *mean curvature*, by H . A point $p \in M$ at which the eigenvalues of A_p agree is called *umbilic* and we define $\hat{M} \subset M$ to be the open submanifold of non-umbilic points.

The pair (g, A) satisfies the Gauss equation

$$|A|_g^2 + 2K_g = (\text{tr}_g A)^2$$

and the Codazzi equations

$${}^g\nabla_X A(Y, Z) = {}^g\nabla_Y A(X, Z)$$

where $X, Y, Z \in \Gamma(TN)$. Conversely, Bonnet's theorem states that if a pair (g, A) on a simply connected surface N satisfies the Gauss - and Codazzi equations, then there exists an immersion $\mathbf{x} : N \rightarrow \mathbb{R}^3$ - unique up to composition with a rigid motion of \mathbb{R}^3 - whose first and second fundamental form are g and A . For this reason we refer to the triple (M, g, A) as *geometric data* of \mathbf{x} .

2.2. The Ricci condition

We suppose from now on that $\mathbf{x} : M \rightarrow \mathbb{R}^3$ is minimal. That is $H \equiv 0$. The Gauss equations imply that $K_g \leq 0$ and that K_g is negative on \hat{M} . It follows from the Codazzi equations that the second fundamental form is divergence free with respect to g . This yields *Simons' identity*

$$\Delta_g A = -|A|_g^2 A$$

where here Δ_g is the rough Laplacian. From

$$4|A|_g^2 {}^g\nabla A|_g^2 = |{}^g\nabla |A|_g^2|^2,$$

Simons' identity, and the Gauss equations we obtain that on \hat{M} the following *Ricci condition*

$$(2.1) \quad \Delta_g \log |K_g| = 4K_g$$

holds. Abbreviate

$$(2.2) \quad u_g = -\frac{1}{4} \log |K_g|,$$

then the Ricci condition becomes

$$\Delta_g u_g = e^{-4u_g}.$$

Conversely, Ricci [22] showed that if g is a Riemannian metric of strictly negative Gauss curvature K_g on a simply connected 2-manifold N satisfying the Ricci condition, then there exists a minimal immersion $\mathbf{x} : N \rightarrow \mathbb{R}^3$ with $\mathbf{x}^*g_E = g$. A proof of this fact using modern language may be found in [6].

2.3. The entropy functional

We will study a certain natural functional \mathcal{E} defined on the space $\mathcal{M}^+(M)$ of smooth Riemannian metrics on M which have positive Gauss curvature. Define for $g \in \mathcal{M}^+(M)$

$$\mathcal{E}[g] = \int_M K_g \log K_g \mu_g$$

This functional has been applied to the study of Ricci flow on surfaces by Hamilton [14] and Chow [7] – in particular Hamilton observed that it is monotonically increasing along the Ricci flow on spheres with positive Gauss curvature (see Section A of the present paper for additional connections to Ricci solitons).

We compute the Euler-Lagrange equations associated to \mathcal{E} . To do so, let f be a smooth symmetric 2-form and write $F = \text{tr}_g f$ for its trace with respect to g . Let $g_t = g + tf$, then (cf. [8, pg. 99])

$$\begin{aligned} \left. \frac{\partial}{\partial t} \right|_{t=0} K_{g_t} &= -\frac{1}{2} \Delta_g F + \frac{1}{2} \text{div}_g(\text{div}_g f) - \frac{1}{2} K_g F \\ &= -\frac{1}{4} \Delta_g F + \frac{1}{2} \text{div}_g \left(\text{div}_g \mathring{f} \right) - \frac{1}{2} K_g F \end{aligned}$$

where \mathring{f} is the trace-free part of f . Hence,

$$\left. \frac{\partial}{\partial t} \right|_{t=0} K_{g_t} \log K_{g_t} = \left(-\frac{1}{4} \Delta_g F + \frac{1}{2} \text{div}_g \left(\text{div}_g \mathring{f} \right) - \frac{1}{2} K_g F \right) (\log K_{g_t} + 1)$$

and so

$$\delta_f \mathcal{E}[g] = \frac{1}{2} \int_M F K_g \log K_g + \left(\text{div}_g \left(\text{div}_g \mathring{f} \right) - \frac{1}{2} \Delta_g F - K_g F \right) (\log K_{g_t} + 1) \mu_g.$$

If f is compactly supported then using Green's formula and the divergence theorem, i.e., integrating by parts twice, yields

$$\delta_f \mathcal{E}[g] = -\frac{1}{4} \int_M F (\Delta_g \log K_g + 2K_g) - 2 \langle f, {}^g \nabla^2 \log K_g \rangle_g \mu_g,$$

where ${}^g \nabla^2$ denotes the trace-free Hessian and $\langle a, b \rangle_g$ the natural bilinear pairing on elements $a, b \in \Gamma(S^2(T^*M))$ obtained via g .

We will say that $g \in \mathcal{M}^+(M)$ is an \mathcal{E} -critical metric if \mathcal{E} is stationary at g with respect to compactly supported conformal deformations. Hence, g is an \mathcal{E} -critical metric if and only if the Gauss curvature K_g of g satisfies

$$\Delta_g \log K_g = -2K_g.$$

As \mathcal{E} is computed purely in terms of geometric quantities it is manifestly diffeomorphism invariant, that is if $\phi : M \rightarrow M$ is a diffeomorphism we have

$$\mathcal{E}[\phi^*g] = \mathcal{E}[g].$$

By Noether's principle this invariance leads to a conservation law for \mathcal{E} -critical metrics. Indeed, let X be a compactly supported vector field on M and ϕ_t the flow of X . We have that

$$\phi_t^*g = g + tL_Xg + o(t).$$

Recall, the Lie derivative, L_Xg can be computed as

$$(L_Xg)(Y, Z) = g({}^g\nabla_Y X, Z) + g({}^g\nabla_Z X, Y).$$

where $Y, Z \in \Gamma(TM)$. By the diffeomorphism invariance we have at an \mathcal{E} -critical metric that

$$\begin{aligned} 0 &= \delta_{L_Xg} \mathcal{E}[g] \\ &= \frac{1}{2} \int_M \langle L_Xg, {}^g\mathring{\nabla}^2 \log K_g \rangle_g \mu_g \\ &= \int_M \operatorname{div}_g \left(({}^g\mathring{\nabla}^2 \log K_g)(X, \cdot) \right) - \langle X, \operatorname{div}_g {}^g\mathring{\nabla}^2 \log K_g \rangle_g \mu_g \\ &= - \int_M \langle X, \operatorname{div}_g {}^g\mathring{\nabla}^2 \log K_g \rangle_g \mu_g \end{aligned}$$

where we used that X has compact support and the divergence theorem. As X is arbitrary,

$$(2.3) \quad \operatorname{div}_g {}^g\mathring{\nabla}^2 \log K_g = 0.$$

In other words, the quantity

$$V_g = {}^g\mathring{\nabla}^2 \log K_g$$

is a trace-free divergence free symmetric 2-form, i.e. a conservation law for the \mathcal{E} functional.

2.4. The entropy form

Let g be a smooth Riemannian metric and ω a smooth real-valued function on M . We note the following standard formula for the trace-free Hessian and the Laplacian operating on $u \in C^\infty(M)$

$$(2.4) \quad \begin{aligned} \Delta_{e^{2\omega}g} u &= e^{-2\omega} \Delta_g u, \\ e^{2\omega} g \mathring{\nabla}^2 u &= g \mathring{\nabla}^2 u - (du \otimes d\omega + d\omega \otimes du - g({}^g\nabla u, {}^g\nabla \omega)g). \end{aligned}$$

Also, the Gauss-curvature transforms under conformal change as

$$K_{e^{2\omega}g} = e^{-2\omega} (K_g - \Delta_g \omega).$$

We let \mathcal{R}_C^\pm denote the space of smooth positively (or negatively) curved Riemannian metrics on M satisfying the *generalized Ricci condition*

$$\Delta_g \log |K_g| = CK_g$$

for some real constant C . In particular, the ε -critical metrics are the elements of \mathcal{R}_{-2}^+ . For $g \in \mathcal{R}_C^\pm$ and $\alpha \in \mathbb{R}$ let $g_\alpha = |K_g|^{2\alpha} g$, then g_α has Gauss-curvature

$$K_{g_\alpha} = (1 - C\alpha)|K_g|^{-2\alpha} K_g$$

which, for $\alpha \neq \frac{1}{C}$, satisfies

$$\Delta_{g_\alpha} \log |K_{g_\alpha}| = \left(\frac{2\alpha - 1}{\alpha - \frac{1}{C}} \right) K_{g_\alpha} = C_\alpha K_{g_\alpha},$$

where

$$C_\alpha = \left(\frac{2\alpha - 1}{\alpha - \frac{1}{C}} \right).$$

It follows that for $\alpha > \frac{1}{C}$ the map φ_α sending g to g_α satisfies

$$\varphi_\alpha : \mathcal{R}_C^\pm \rightarrow \mathcal{R}_{C_\alpha}^\mp$$

whereas for $\alpha < \frac{1}{C}$

$$\varphi_\alpha : \mathcal{R}_C^\pm \rightarrow \mathcal{R}_{C_\alpha}^\pm.$$

Note that the choice $\alpha = \frac{1}{C}$ maps the elements of \mathcal{R}_C^\pm to flat metrics and the choice $\alpha = \frac{1}{2}$ (assuming $C \neq 2$) maps the elements of \mathcal{R}_C^\pm to metrics of non-zero constant Gauss curvature.

Suppose $g \in \mathcal{R}_4^-$, then $\hat{g} = g_{3/8}$ is an ε -critical metric with Gauss curvature

$$K_{\hat{g}} = \frac{1}{2}|K_g|^{1/4}.$$

It follows with (2.2) and (2.3) that the symmetric trace-free *entropy form*

$$\begin{aligned} T &:= V_{\hat{g}} = \hat{g} \hat{\nabla}^2 \log K_{\hat{g}} = \hat{g} \hat{\nabla}^2 \left(\frac{1}{4} \log |K_g| \right) \\ &= -\hat{g} \hat{\nabla}^2 u_g = -g \nabla^2 u_g - 3 \left((du_g)^2 - \frac{1}{2} g(g \nabla u_g, g \nabla u_g) g \right) \end{aligned}$$

is divergence-free with respect to \hat{g} .

If M is oriented, then we call the associated quadratic differential $P := T + iJT$ the *entropy differential*. Since the condition on a symmetric 2-form on M to be trace-free and divergence free is conformally invariant, we obtain:

Theorem 2.1. *Let (M, g) be a smooth oriented Riemannian 2-manifold with $K_g < 0$ and g satisfying the Ricci condition. Then the entropy differential $P = T + iJT$ is holomorphic.*

Remark 2.2. Note that a metric of negative Gauss-curvature on a surface arising via a constant mean curvature 2 immersion into hyperbolic 3-space \mathbb{H}^3 also satisfies the Ricci condition (recall that with our convention the ‘mean’ curvature is the sum of the principal curvatures). Besides satisfying the Ricci condition, these so-called *Bryant surfaces* share many properties with minimal surfaces in Euclidean 3-space, the most important being that they possess a Weierstrass representation [4]. In particular, a quadratic

differential similar to the one studied here has been defined for surfaces of constant mean curvature one in hyperbolic three-space \mathbb{H}^3 by Bryant [4] and for surfaces of Bryant type in the Lorentz-Minkowski four-space \mathbb{L}^4 by Aledo, Galvez and Mira [1].

2.5. The inverse problem

Suppose we are given a Riemann surface (M, J) and a holomorphic quadratic differential P on M . We ask whether we can locally find a J -compatible metric g of negative Gauss curvature on M which satisfies the Ricci condition and so that the entropy differential of g is P .

Let $z : V \rightarrow \mathbb{C}$ be local holomorphic coordinates on (M, J) . It is easy to check that if the real-valued function u solves Liouville's equation

$$(2.5) \quad 4\partial_{z\bar{z}}^2 u = e^{-2u},$$

then the metric $g = e^{2u}|dz|^2$ satisfies the Ricci condition and $u_g = -\frac{1}{4} \log |K_g| = u$. Now a straightforward computation yields

$$\begin{aligned} \operatorname{Re}(P) = T &= -g_0 \mathring{\nabla}^2 u - du^2 + \frac{1}{2} g_0 (g_0 \nabla u, g_0 \nabla u) g_0 \\ &= -2 \operatorname{Re} \left(\left(\partial_{zz}^2 u + (\partial_z u)^2 \right) dz^2 \right) \end{aligned}$$

where $g_0 = |dz|^2$. Writing $P = \frac{\rho}{2} dz^2$ for some holomorphic function ρ on V , we are thus interested in the solutions u of the system

$$4\partial_{z\bar{z}}^2 u = e^{-2u}, \quad \partial_{zz}^2 u + (\partial_z u)^2 = -\frac{\rho}{4}.$$

Lemma 2.3. *Let $V \subset \mathbb{C}$ be a simply-connected domain and ρ a holomorphic function on V . We let z be the usual complex coordinate on \mathbb{C} . Then there exist holomorphic functions w_1, w_2 on V solving the equation*

$$(2.6) \quad \partial_{zz}^2 w + \frac{\rho}{4} w = 0$$

and with Wronskian satisfying

$$(2.7) \quad W(w_1, w_2) = w_1 \partial_z w_2 - w_2 \partial_z w_1 = \frac{1}{2}.$$

If \hat{w}_1, \hat{w}_2 is another pair of holomorphic solutions to (??) satisfying (??), then there is a unique matrix $B \in \operatorname{SL}(2, \mathbb{C})$ so that $\hat{\mathbf{w}} = B\mathbf{w}$ where

$$\mathbf{w} = \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} \quad \text{and} \quad \hat{\mathbf{w}} = \begin{pmatrix} \hat{w}_1 \\ \hat{w}_2 \end{pmatrix}.$$

Proof. See for instance [15, Chapter 5.2]. □

We now have the following:

Proposition 2.4. *Let $V \subset \mathbb{C}$ be a simply-connected domain and suppose that ρ is a holomorphic function on V . Then every real-valued function $u \in C^\infty(V)$ that satisfies the system*

$$(2.8) \quad 4\partial_{z\bar{z}}^2 u = e^{-2u}, \quad \partial_{zz}^2 u + (\partial_z u)^2 = -\frac{\rho}{4},$$

is of the form

$$u_{\mathbf{w}} = \log |\mathbf{w}|^2 = \log (|w_1|^2 + |w_2|^2),$$

where

$$\mathbf{w} = \begin{pmatrix} w_1 \\ w_2 \end{pmatrix}$$

and w_1, w_2 satisfy (??) and (??). Hence, for each ρ there is a three-dimensional space $\mathrm{SL}(2, \mathbb{C})/\mathrm{SU}(2)$ of solutions u .

Proof. On $X = V \times \mathbb{R} \times \mathbb{C}$ with coordinates (z, u, q) consider the rank 2 subbundle $E \subset TX$ defined by the common kernel of the 1-forms

$$\varphi_1 = du - qdz - \bar{q}d\bar{z}, \quad \varphi_2 = dq + \left(\frac{\rho}{4} + q^2\right) dz - \frac{1}{4}e^{-2u}d\bar{z}.$$

Now

$$d\varphi_1 = dz \wedge \varphi_2 + d\bar{z} \wedge \overline{\varphi_2},$$

$$d\varphi_2 = -\frac{1}{2}e^{-2u}d\bar{z} \wedge \varphi_1 - 2qdz \wedge \varphi_2,$$

hence E is Frobenius integrable. Furthermore, the 1-graph

$$z \mapsto (z, u(z), \partial_z u(z))$$

of a solution u to (2.8) is an integral manifold of E . Consequently, a solution u to (2.8) is uniquely determined by specifying u and $\partial_z u$ at some point $z_0 \in V$. Simple computations show that for any $(z_0, u_0, q_0) \in X$ there exist holomorphic map $\mathbf{w} : V \rightarrow \mathbb{C}^2$ satisfying (Equation (2.6), Equation (2.7)) so that $u_{\mathbf{w}} = \log |\mathbf{w}|^2$ solves (2.8) and satisfies

$$u(z_0) = u_0, \quad \partial_z u(z_0) = q_0.$$

Clearly, if $\hat{\mathbf{w}} = U\mathbf{w}$ for $U \in \mathrm{SU}(2)$, then $u_{\hat{\mathbf{w}}} = u_{\mathbf{w}}$. □

Corollary 2.5. *Let $V \subset \mathbb{C}$ be a simply-connected domain and suppose that ρ is a holomorphic function on V . Let*

$$g_{\mathbf{w}} = |\mathbf{w}|^4 |dz|^2 \quad \text{and} \quad A = \mathrm{Re}(dz^2)$$

where

$$\mathbf{w} = \begin{pmatrix} w_1 \\ w_2 \end{pmatrix}$$

and w_1, w_2 satisfy (??) and (??). Then there is a minimal immersion $\mathbf{x}_{\mathbf{w}} : V \rightarrow \mathbb{R}^3$ with geometric data $(V, g_{\mathbf{w}}, A)$ and entropy differential $P = \frac{\rho}{2} dz^2$.

Proof. This is an immediate consequence of Theorem 2.4 and the fundamental theorem of submanifold geometry. □

3. Weierstrass Representation

In this section we express the entropy differential P in terms of the Weierstrass data of the minimal surface Σ – this allows us to compute P more readily and to easily analyze its singular and asymptotic behavior.

3.1. The Weierstrass Representation

Recall, to an oriented minimal surface Σ in \mathbb{R}^3 with parametrization $\mathbf{x}_\Sigma : M \rightarrow \Sigma$ one can associate *Weierstrass data* which encodes the surface and parametrization \mathbf{x}_Σ in complex analytic data. More precisely, the Weierstrass data associated to \mathbf{x}_Σ is the quadruple (M, J, G, η) where (M, J) is a Riemann surface, G is a meromorphic function on (M, J) and η a holomorphic one form on (M, J) . The data is determined as follows:

- (1) J is the almost-complex structure induced by \mathbf{x}_Σ ;
- (2) $G = S \circ \mathbf{n}$ where \mathbf{n} is the Gauss map and

$$S : \partial B_1 \setminus (0, 0, -1) \rightarrow \mathbb{C}$$

is stereographic projection;

- (3) $\mathbf{x}_\Sigma^* dx_3 = \operatorname{Re} \eta$.

The Weierstrass data allows one to reconstruct \mathbf{x}_Σ by the means of the *Weierstrass representation*:

$$(3.1) \quad \mathbf{x}_\Sigma(p) - \mathbf{x}_\Sigma(p_0) = \operatorname{Re} \int_{p_0}^p \left(\frac{1}{2}(G^{-1} - G), \frac{i}{2}(G^{-1} + G), 1 \right) \eta.$$

Conversely, given any quadruple (M, J, G, η) we may use (??) to construct a parametrization \mathbf{x}_Σ of a branched minimal surface Σ provided:

- (1) Both $G\eta$ and $G^{-1}\eta$ are holomorphic;
- (2) For any 1-cycle γ in M :

$$\int_\gamma \left(\frac{1}{2}(G^{-1} - G), \frac{i}{2}(G^{-1} + G), 1 \right) \eta \in i\mathbb{R}^3.$$

Condition (??) is known as the period condition.

Remark 3.1. The parametrizing map \mathbf{x}_Σ is an immersion if and only if $G\eta$, $G^{-1}\eta$, and η do not all simultaneously vanish at any point of M .

It is convenient to choose a local complex coordinate patch (V, z) on M and to write $\eta = h dz$ and $G = G(z)$. We write f' for $\partial_z f$ for any function $f \in C^1(V, \mathbb{C})$. Standard computations (see for instance [17]) give the metric as

$$g = \mathbf{x}_\Sigma^* g_E = \frac{1}{4}(|G| + |G|^{-1})^2 \eta \otimes \bar{\eta} = \frac{|h|^2}{4}(|G| + |G|^{-1})^2 |dz|^2,$$

the Hopf differential as

$$Q = -\frac{1}{G} dG \circ \eta = -\frac{hG'}{G} dz^2,$$

and the Gauss curvature

$$K_g = -\frac{16|GG'|^2}{|h|^2(1 + |G|^2)^4}.$$

Hence,

$$u_g = -\log 2 - \frac{1}{4} \log |h^{-1}GG'|^2 + \log(1 + |G|^2).$$

3.2. Computing P in terms of Weierstrass data

We now compute the entropy differential P in terms of the Weierstrass data.

Proposition 3.2. *Let Σ be an oriented minimal surface in \mathbb{R}^3 with Weierstrass data (M, J, G, η) . If (U, z) is a coordinate chart of M on which $K_g < 0$ and we write $\eta = h dz$, $G = G(z)$, then $P = \frac{\rho}{2} dz^2$ with*

$$\rho = \left(\frac{G'''}{G'} + \frac{G''}{2G} - \frac{3(G')^2}{4G^2} - \frac{7(G'')^2}{4(G')^2} + \frac{G''h'}{2G'h} - \frac{G'h'}{2Gh} - \frac{h''}{h} + \frac{5(h')^2}{4h^2} \right).$$

If $Q = dz^2$, then

$$\begin{aligned} P &= \left(\left(\frac{G''}{G'} \right)' - \frac{1}{2} \left(\frac{G''}{G'} \right)^2 \right) dz^2 \\ &= \{G, z\} dz^2, \end{aligned}$$

where $\{G, z\}$ is the Schwarzian derivative of G .

Remark 3.3. The Schwarzian derivative of G has also been studied from a different perspective by Duren, Chuaqui and Osgood [9] (see also [5] for a coordinate free definition of the Schwarzian derivative).

Proof. If $K_g < 0$ on V , then $\frac{hG'}{G}$ has no zeroes on V . Hence, if V is simply connected there is global square root of $-\frac{hG'}{G}$. Indeed, there is a function w on V so that

$$dw = \sqrt{-\frac{hG'}{G}} dz$$

and so

$$Q = dw^2.$$

The exact one-form dw is well-defined up to multiplication by ± 1 . In particular, we have that the entropy differential is given by

$$P = -2 \left(\partial_{ww}^2 u_g + (\partial_w u_g)^2 \right) dw^2.$$

In order to express P in terms of the Weierstrass data we note that:

$$\partial_w = \sqrt{-\frac{G}{hG'}} \partial_z$$

and so

$$\partial_{ww}^2 = -\frac{G}{hG'} \partial_{zz}^2 - \frac{G}{2hG'} \left(\frac{G'}{G} - \frac{G''}{G'} - \frac{h'}{h} \right) \partial_z.$$

Hence,

$$\begin{aligned} \sqrt{-\frac{hG'}{G}} \partial_w u_g &= -\frac{1}{4} \frac{(h^{-1}GG')'}{h^{-1}GG'} + \frac{G'\bar{G}}{1+|G|^2} \\ &= \frac{1}{4} \left(\frac{h'}{h} - \frac{G'}{G} - \frac{G''}{G'} \right) + \frac{G'\bar{G}}{1+|G|^2} \end{aligned}$$

and

$$\begin{aligned} -\frac{hG'}{G}\partial_{ww}^2 u_g = & \frac{1}{4} \left(\frac{h''}{h} - \left(\frac{h'}{h} \right)^2 - \frac{G''}{G} + \left(\frac{G'}{G} \right)^2 - \frac{G'''}{G'} + \left(\frac{G''}{G'} \right)^2 \right) + \\ & + \frac{G''\bar{G}}{1+|G|^2} - \left(\frac{G'G}{1+|G|^2} \right)^2 + \frac{1}{8} \left(\frac{G''}{G'} \right)^2 - \frac{1}{8} \left(\frac{h'}{h} - \frac{G'}{G} \right)^2 - \\ & - \frac{1}{2} \left(\frac{G''}{G'} + \frac{h'}{h} - \frac{G'}{G} \right) \frac{G'\bar{G}}{1+|G|^2}. \end{aligned}$$

We note that both these expressions are independent of replacing w by $-w$ and so hold even if V is not simply-connected. Combining the above we determine that $P = \frac{\rho}{2} dz^2$ with

$$\rho = \left(\frac{G'''}{G'} + \frac{G''}{2G} - \frac{3(G')^2}{4G^2} - \frac{7(G'')^2}{4(G')^2} + \frac{G''h'}{2G'h} - \frac{G'h'}{2Gh} - \frac{h''}{h} + \frac{5(h')^2}{4h^2} \right).$$

as claimed. If $Q = dz^2$, then

$$h = -\frac{G}{G'}$$

and so

$$\frac{h'}{h} = \frac{G'}{G} - \frac{G''}{G'}$$

and

$$\frac{h''}{h} = -\frac{G''}{G} + 2\frac{(G'')^2}{(G')^2}.$$

Plugging these into the formula for P gives

$$P = \left(\left(\frac{G''}{G'} \right)' - \frac{1}{2} \left(\frac{G''}{G'} \right)^2 \right) dz^2.$$

□

As an application of the previous computation, we determine the behavior of the entropy differential at umbilic points of Σ :

Corollary 3.4. *If Σ is a minimal surface in \mathbb{R}^3 and $p \in \Sigma$ an isolated umbilic point, then P , the entropy differential of Σ , has a double pole at p . Indeed, there is a complex coordinate z around p satisfying $z(p) = 0$ and so*

$$P = - \left(\frac{3n^2 + 4n}{8} \right) \frac{dz^2}{z^2} + O(1),$$

where n is the order of vanishing of the Hopf differential Q at p .

Proof. By rotating Σ in \mathbb{R}^3 , we may assume that $\mathbf{n}(p) = \mathbf{e}_1$ where $(\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3)$ denotes the standard basis of \mathbb{R}^3 . Hence, there is p -neighborhood V with a p -centered complex coordinate z , together with Weierstrass data (V, J, G, η) parametrizing Σ near p which satisfies $\eta = dz$ and $G(z) = 1 + o(1)$. In fact, there are $a, b \in \mathbb{C}$ with $a \neq 0$ so that

$$G(z) = 1 + az^{n+1} + bz^{n+2} + O(z^{n+2}),$$

because the umbilic point is isolated. Indeed,

$$Q = -\frac{hG'}{G}dz^2 = -a(n+1)z^n dz^2 + O(z^n)$$

and n is the order of vanishing of Q at p .

We let $V^* = V \setminus \{p\}$ and apply [Theorem 3.2](#) to compute that

$$P = \frac{1}{2} \left(-\left(\frac{3}{4}n^2 + n\right)z^{-2} - \frac{3}{2} \frac{n(n+2)}{n+1} \frac{b}{a} z^{-1} \right) dz^2 + O(1).$$

However, by changing coordinates to $z \rightarrow z + cz^2$ for an appropriate choice of c we obtain P in the desired form. \square

We may also use [Proposition \(??\)](#) to compute the entropy differential at branch points.

Corollary 3.5. *Suppose that (M, J) is a Riemann surface and $\mathbf{x} : M \rightarrow \Sigma \subset \mathbb{R}^3$ is a non-flat branched minimal immersion. Let $p \in M$ be a branch point of M of order n and index k .*

- (1) *If $n - k + 1 \neq 0$, then the entropy differential, P , has a double pole at p and there is a complex coordinate patch (V, z) about p with $z(p) = 0$ so that*

$$P = \left(\frac{(n+k+1)^2 - 4k^2}{8} \right) \frac{dz^2}{z^2} + O(1);$$

- (2) *If $n - k + 1 = 0$, then P has at most a simple pole at p .*

Proof. We may pick a complex coordinate patch (V, z) about p so that $z(p) = 0$ and on $V^* = V \setminus \{p\}$ the parameterization \mathbf{x} is a smooth immersion. Let $(z(V^*), J, G, \eta)$ be the Weierstrass data of this immersion where here J is the usual complex structure. As \mathbf{x} has an order $n \geq 1$ branch point with index k at $z(p) = 0$, up to an ambient rotation of \mathbb{R}^3 and a re-parameterization the data has the form

$$G(z) = z^k$$

for $k \geq 1$ and

$$\eta = (az^{n+k} + bz^{n+k+1}) dz + O(z^{n+k+2})$$

where $a \neq 0$. Computing gives

$$\begin{aligned} P &= \left(\frac{(n+k+1)^2 - 4k^2}{8z^2} + \frac{\frac{b}{a}(n+k-1)}{4z} \right) dz^2 + O(1) \\ &= \left(\frac{(n-k+1)(n+3k+1)}{8z^2} + \frac{\frac{b}{a}(n+k-1)}{4z} \right) dz^2 + O(1). \end{aligned}$$

The corollary follows by noting that if $n - k + 1 = 0$, then P has at most a simple pole at p as claimed. If $n - k + 1 \neq 0$, then P has a double pole and may be put in the claimed form by replacing z by $z + cz^2$ for an appropriate choice of c . \square

Remark 3.6. We do not distinguish between true and false branch points. However, any false branch point of a smooth minimal surface at a point with non-vanishing curvature must have order of vanishing n and index $n + 1$.

3.3. Hill's equation and the (spinor) Weierstrass representation

We conclude by relating the solutions w_1, w_2 from [Theorem 2.4](#) to the Weierstrass data. We observe a connection with the spinorial Weierstrass representation of [\[18\]](#) but do not explore this in depth.

Proposition 3.7. *Fix a simply-connected domain $V \subset \mathbb{C}$. Suppose $(V, J_{std}, G, h \, d\mathbf{z})$ is the Weierstrass data of a minimal immersion with Hopf differential $Q = dz^2$ and entropy differential $P = \frac{\rho}{2} dz^2$, then*

$$\begin{aligned} w_1(z) &= \frac{\sqrt{2}}{2} \sqrt{-G^{-1}(z)h(z)} \\ w_2(z) &= \frac{\sqrt{2}}{2} \sqrt{-G(z)h(z)} \end{aligned}$$

are single-valued and satisfy (??). Furthermore, w_1 and w_2 satisfy (??) provided the branches of the square-root are chosen so $\frac{w_2}{w_1} = G$.

Proof. As G and $h \, d\mathbf{z}$ is the Weierstrass data of a minimal immersion, Gh or $G^{-1}h$ do not have a pole on V . Moreover, if either function vanished at a point z_0 , then $h(z_0) = 0$. As $Q = dz^2$, $-\frac{G'}{G}h = 1$. Because G is meromorphic, h has at most a simple zero at z_0 and so G has either a simple pole or a simple zero at z_0 . Hence, at z_0 either $Gh \neq 0$ and $G^{-1}h$ has a double zero or $G^{-1}h \neq 0$ and Gh has a double zero. Taken together this implies that w_1 and w_2 are single-valued.

A straightforward computation gives that w_1, w_2 satisfy the Wronskian condition (??). Differentiating (??) once, gives that

$$\frac{w_1''}{w_1} = \frac{w_2''}{w_2} = -\frac{\hat{\rho}}{4}$$

for a meromorphic function $\hat{\rho}$. It is a classical fact – see for instance [\[15\]](#) – that if \hat{w}_1, \hat{w}_2 solve $w'' + \frac{\hat{\rho}}{4}w = 0$, then $\hat{G} = \frac{\hat{w}_1}{\hat{w}_2}$ satisfies $\{\hat{G}, z\} = \frac{\hat{\rho}}{2}$. As $\frac{w_2}{w_1} = G$, this implies that $\hat{\rho} = 2\{G, z\} = \rho$ and so w_1, w_2 satisfy (??). \square

Corollary 3.8. *Let $V \subset \mathbb{C}$ be a fixed simply-connected domain. If ρ is a holomorphic function on V and $\mathbf{w} = (w_1, w_2)^\top$ satisfies (??) and (??), then the minimal immersion $\mathbf{x}_{\mathbf{w}}$ of [Theorem 2.5](#) may be chosen to have Weierstrass data (V, J_{std}, G, η) , where*

$$G = \frac{w_2}{w_1} \quad \text{and} \quad \eta = -2w_1w_2dz.$$

Remark 3.9. If we let $s_i = w_i\sqrt{dz}$ be holomorphic spinors, then the s_i are (up to choices of normalization) the spinor Weierstrass data of [\[18\]](#).

Proof. Set $G = \frac{w_2}{w_1}$ and $\eta = -2w_1w_2dz$ and let $\mathbf{x}_{\mathbf{w}}$ be the minimal immersion corresponding to this data. As $w_1 = \frac{\sqrt{2}}{2} \sqrt{-G^{-1}(z)h(z)}$ and $w_2 = \frac{\sqrt{2}}{2} \sqrt{-G(z)h(z)}$, [Theorem 3.7](#) implies that the entropy differential of $\mathbf{x}_{\mathbf{w}}$ is

$\frac{\rho}{2}dz^2$. A direct computation and (??) imply that the Hopf differential of $\mathbf{x}_{\mathbf{w}}$ is dz^2 . Finally,

$$\mathbf{x}_{\mathbf{w}}^*g_E = \frac{1}{4}|h|^2 \left(|G| + |G^{-1}| \right)^2 |dz|^2 = |\mathbf{w}|^4 dz \otimes d\bar{z} = g_{\mathbf{w}}.$$

Hence, $\mathbf{x}_{\mathbf{w}}$ satisfies the conclusions of [Theorem 2.5](#) which verifies the claim. \square

4. Characterization of Minimal Surfaces in Terms of the Entropy Differential

In this section we characterize a number of classical minimal surfaces in terms of the entropy form. In particular, we show that the entropy form vanishes if and only if the surface is contained in Enneper's surface. The catenoid and helicoid are also characterized in terms of a simple relationship between the entropy form and the second fundamental form.

4.1. Deformed Catenoids and Helicoids

In order to get a complete characterization we must introduce two one-parameter families of surfaces, \mathcal{C} and \mathcal{H} , which we call, respectively, deformed catenoids and deformed helicoids. Specifically, \mathcal{C} is the family of surfaces C_t with Weierstrass data

$$\left(\mathbb{C}, J, \frac{t - e^z}{1 - te^z}, \frac{1}{1 - t^2}(1 - te^{-z})(1 - te^z)dz \right).$$

Similarly, \mathcal{H} is the family of surfaces H_t with Weierstrass data

$$\left(\mathbb{C}, J, \frac{t - e^z}{1 - te^z}, \frac{-i}{1 - t^2}(1 - te^{-z})(1 - te^z)dz \right).$$

In both cases, z is the usual coordinate on \mathbb{C} , J the usual complex structure and $t \in (-1, 1)$. In particular, C_0 is the vertical catenoid and H_0 is the vertical helicoid. Computing as in the preceding section we obtain that for surfaces in \mathcal{C}

$$P = -\frac{1}{2}dz^2 = \frac{1}{2}Q,$$

and for surfaces in \mathcal{H}

$$P = -\frac{1}{2}dz^2 = \frac{i}{2}Q.$$

We remark that \mathcal{C} and \mathcal{H} are obtained from C_0 and from H_0 by applying the one parameter family of Möbius transforms

$$B_t : z \mapsto \frac{t + z}{1 - tz}$$

to the Gauss maps of C_0 and H_0 .

Writing $z = x + iy$ and integrating (??) gives the parameterizations of $C_t \in \mathcal{C}$:

$$\mathbf{F}_t^{\mathcal{C}}(x, y) = \mathbf{F}_0^{\mathcal{C}}(x, y) + \frac{2t}{1 - t^2} (0, -y + t \cosh x \sin y, tx - \sinh x \cos y);$$

$$\mathbf{F}_0^{\mathcal{C}}(x, y) = (\cosh x \cos y, \cosh x \sin y, x).$$

Here \mathbf{F}_0^C is a parameterization of (an infinite cover of) the catenoid. By inspection, C_t has $\Pi_2 = \{x_2 = 0\}$ and $\Pi_3 = \{x_3 = 0\}$ as planes of reflectional symmetry. Moreover,

$$\mathbf{F}_t^C(x, y + 2\pi) = \mathbf{F}_t^C(x, y) - \frac{4\pi t}{1 - t^2} \mathbf{e}_2$$

and so C_t is singly-periodic. When $t \neq 0$, it is straightforward to see that C_t is not embedded. Suppose E_θ is the rotation of the upper half of C_0 by θ around the x_2 -axis. One verifies that C_t is close to the union of translates of E_θ and of $E_{\pi-\theta}$ where here $\theta = \tan^{-1}\left(\frac{2t}{1-t^2}\right)$.

Similarly, elements of \mathcal{H} are parametrized by

$$\mathbf{F}_t^{\mathcal{H}}(x, y) = \mathbf{F}_0^{\mathcal{H}}(x, y) + \frac{2t}{1 - t^2} (0, x + t \sinh x \cos y, ty - \cosh x \sin y);$$

$$\mathbf{F}_0^{\mathcal{H}}(x, y) = (\sinh x \sin y, -\sinh x \cos y, y).$$

For $t = 0$ this is a parametrization of the helicoid. Note that the image of $\{x = 0\}$ is the x_3 -axis while the image of $\{y = n\pi\}$ for n an integer are the set of parallel lines $\{x_1 = 0, x_3 = \frac{1+t^2}{1-t^2}n\pi\}$ contained in the $\{x_1 = 0\}$ plane. Moreover,

$$\mathbf{F}_t^{\mathcal{H}}(x, y + 2\pi) = \mathbf{F}_t^{\mathcal{H}}(x, y) + 2\pi \frac{1 - t^2}{1 + t^2} \mathbf{e}_3$$

so H_t is singly-periodic. For $t \neq 0$, H_t is not embedded. However, if we denote by H_t^\pm the two components of $H_t \setminus \{x_1 = x_2 = 0\}$, then each H_t^\pm is embedded. In fact, each is a multi-valued graphs over the plane Π_θ which contains the x_2 -axis and makes an angle $\theta = \tan^{-1}\left(\frac{2t}{1-t^2}\right)$ with the plane $\Pi_3 = \{x_3 = 0\}$. In particular, rotating H_t^\pm by θ around the x_2 -axis gives a surface that looks (roughly) like a sheared copy of H_0^\pm .

4.2. Characterization of minimal surfaces in terms of P and Q

We now characterize surfaces in terms of simple relationships between P and Q . In light of [Theorem 2.4](#), we expect there to be a three-parameter family of surfaces for any fixed of P and Q . However, in simple settings two of these parameters correspond to re-parameterizations.

Theorem 4.1. *Let Σ be a smooth oriented non-flat minimal surface in \mathbb{R}^3 with Hopf differential Q and entropy differential P . We have:*

- (1) *If $P \equiv 0$, then up to a rigid motion and homothety, Σ is contained in Enneper's surface;*
- (2) *If $\lambda \neq 0$ and $P \equiv \lambda Q$, then, up to a rigid motion and homothety, Σ is contained in a surface $C \in \mathcal{C}$. If Σ is properly embedded, then it is the catenoid;*
- (3) *If $\lambda \neq 0$ and $P \equiv iQ$, then, up to a rigid motion and homothety, Σ is contained in a surface $H \in \mathcal{H}$. If Σ is properly embedded, then it is the helicoid.*

Remark 4.2. If Σ is an oriented minimal surface in \mathbb{R}^3 with Hopf differential Q and entropy differential P , then for any $\lambda > 0$ the rescaling scaling of $\lambda\Sigma$

has Hopf differential λQ and entropy differential P . Reversing the orientation of Σ changes Q to $-Q$ but leaves P unchanged.

Proof. After possibly rescaling Σ and reversing the orientation, we may assume that $P = -\frac{1}{2}\alpha^2 dz^2$ where $\alpha = 0$ in Case (??), $\alpha^2 = 1$ in Case (??) and $\alpha^2 = i$ in Case (??). As Σ is smooth and non-flat, the second fundamental form has no singularities and P can only have isolated singularities. Hence, by [Theorem 3.4](#), in all cases P has no singularities and Q has no zeros on Σ . Hence, for any point $p \in \Sigma$ there is a simply connected neighborhood V of p and complex coordinate $z : V \rightarrow \mathbb{C}$ so that the Hopf differential satisfies $Q = -dz^2$. That is, $P = \frac{\alpha^2}{2} dz^2$. By [Theorem 3.8](#), in order to recover the surface it is enough to understand the holomorphic solutions on $z(V)$ to the Hill's equation:

$$(4.1) \quad \partial_{zz}^2 w - \frac{\alpha^2}{4} w = 0.$$

Clearly, this equation makes sense on all of \mathbb{C} (with z as the usual coordinate) and analytic continuation implies that all solutions are obtained by restricting global solutions to $z(V)$. Let $\mathbf{w}(z) = (w_1(z), w_2(z))^T$ be a pair of solution to the Hill's equation with Wronskian $W(w_1, w_2) = \frac{1}{2}$.

We note there are two natural actions on the space of solutions. The first is the natural action of $\mathrm{SL}(2, \mathbb{C})$ of [Theorem 2.4](#) which is transitive. The second is an action of \mathbb{C} that arises from the translation invariance of (4.1). Specifically, let \mathbb{C} act on \mathbf{w} by $\tau \mapsto \mathbf{w}(z + \tau)$. The translation invariance of (4.1) and of the Wronskian condition implies that this is a well defined action. By [Theorem 2.4](#), the action of $\mathrm{SU}(2) \subset \mathrm{SL}(2, \mathbb{C})$ does not change the geometry of the surface. Likewise, the action of \mathbb{C} amounts to a change of coordinates and also does not change the geometry. Our goal is to determine all geometrically distinct solutions.

First, note that the Gram-Schmidt procedure implies that any matrix $B \in \mathrm{SL}(2, \mathbb{C})$ may be factored as

$$B = UL$$

where $U \in \mathrm{SU}(2)$ and $L \in \mathrm{SL}(2, \mathbb{C})$ is lower triangular with positive entries on the diagonal and $\det L = 1$. This is sometimes called the QR (or in this case QL) factorization. We write any such L as

$$L = \begin{bmatrix} \mu & 0 \\ \nu & \mu^{-1} \end{bmatrix}$$

where $\mu > 0$ and $\nu \in \mathbb{C}$. We now treat the case $\alpha = 0$ and $\alpha \neq 0$ separately.

Case (??): By inspection a pair of solutions to (4.1) with $\alpha = 0$ and satisfying the Wronskian condition are

$$w_1(z) = 1 \text{ and } w_2(z) = \frac{1}{2}z.$$

Hence, by the QL factorization, the functions

$$w_1(z) = \mu \text{ and } w_2(z) = \nu + \frac{1}{2}\mu^{-1}z,$$

with $\mu > 0$ and $\nu \in \mathbb{C}$ give all geometrically distinct solutions to (4.1). Applying the translation action with $\tau = -2\mu\nu$ gives all geometrically distinct solutions in the form

$$w_1(z) = \mu \text{ and } w_2(z) = \frac{1}{2}\mu^{-1}z.$$

By Theorem 3.8 the Gauss map the associated minimal surfaces maybe chosen so

$$G(z) = \frac{w_2}{w_1} = \frac{z}{2\mu^2}.$$

Moreover, as $Q = -dz^2$ the height differential is $\eta = zdz$. This is precisely the Weierstrass data of a rescaling of Enneper's surface proving the claim in this case.

Case (??) and (??): As $\alpha \neq 0$, a pair of solutions to (4.1) that satisfy the Wronskian condition are

$$w_1(z) = \frac{1}{\sqrt{2\alpha}}e^{-\frac{\alpha}{2}z} \text{ and } w_2(z) = \frac{1}{\sqrt{2\alpha}}e^{\frac{\alpha}{2}z}.$$

Hence, by the QL factorization, we may write all geometrically distinct solutions to (4.1) in the form

$$w_1(z) = \frac{\mu}{\sqrt{2\alpha}}e^{-\frac{\alpha}{2}z} \text{ and } w_2(z) = \frac{1}{\sqrt{2\alpha}}\left(\nu e^{-\frac{\alpha}{2}z} + \mu^{-1}e^{\frac{\alpha}{2}z}\right)$$

with $\mu > 0$ and $\nu \in \mathbb{C}$. The translation action allows us to express all geometrically distinct solutions as

$$w_1(z) = i\frac{e^{-i\theta/2}}{\sqrt{2\alpha}}e^{-\frac{\alpha}{2}z} \text{ and } w_2(z) = i\frac{e^{i\theta/2}}{\sqrt{2\alpha}}\left(\gamma e^{-\frac{\alpha}{2}z} - e^{\frac{\alpha}{2}z}\right).$$

where $\gamma \geq 0$ and $\theta \in [0, 2\pi)$. Indeed, either $\nu = 0$ and we take $\gamma = \theta = 0$ or $\nu \neq 0$ and we write $\nu = \gamma\mu e^{i\theta}$. In both cases, we act by $\tau = \frac{1}{\alpha}i(\theta - \pi) + \frac{2}{\alpha}\ln \mu$. Let $\phi \in (-\pi/4, \pi/4)$ satisfy

$$\tan 2\phi = \gamma.$$

The matrix

$$\begin{pmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{pmatrix} \begin{pmatrix} -ie^{i\theta/2} & 0 \\ 0 & -ie^{-i\theta/2} \end{pmatrix}$$

is the product of two elements of $SU(2)$ and so is in $SU(2)$. Acting by this matrix gives that all geometrically distinct solutions can be put in the form

$$w_1(z) = \frac{\cos \phi}{\sqrt{2\alpha} \cos 2\phi}e^{-\frac{\alpha}{2}z} - \frac{\sin \phi}{\sqrt{2\alpha}}e^{\frac{\alpha}{2}z}$$

and

$$w_2(z) = \frac{\sin \phi}{\sqrt{2\alpha} \cos 2\phi}e^{-\frac{\alpha}{2}z} - \frac{\cos \phi}{\sqrt{2\alpha}}e^{\frac{\alpha}{2}z},$$

where $\phi \in (-\pi/4, \pi/4)$. By applying the translation action with $\tau = -\frac{1}{\alpha}\ln \cos 2\phi$, all geometrically distinct solutions can be put in the simplified form

$$w_1(z) = \frac{\cos \phi e^{-\frac{\alpha}{2}z} - \sin \phi e^{\frac{\alpha}{2}z}}{\sqrt{2\alpha} \cos 2\phi} \text{ and } w_2(z) = \frac{\sin \phi e^{-\frac{\alpha}{2}z} - \cos \phi e^{\frac{\alpha}{2}z}}{\sqrt{2\alpha} \cos 2\phi}.$$

By [Theorem 3.8](#) the Gauss map the associated minimal surfaces may be chosen so

$$G(z) = \frac{w_2}{w_1} = \frac{\tan \phi - e^{\alpha z}}{1 - \tan \phi e^{\alpha z}}.$$

Set $t = \tan \phi$. If $\alpha^2 = 1$, then we may take $\alpha = 1$ and as $Q = -dz^2$ we see that $\eta = \frac{1}{1-t^2}(1-te^{-z})(1-te^z)dz$ which together with $G(z)$ is precisely the data of a deformed catenoid. If $\alpha^2 = i$, then we write $\zeta = \alpha z$. In this case $Q = -\frac{1}{\alpha^2}d\zeta^2 = id\zeta^2$ and so $\eta = -\frac{i}{1-t^2}(1-te^{-\zeta})(1-te^\zeta)d\zeta$ which together with $G(\zeta)$ is precisely the data of a deformed helicoid. \square

5. Curvature Estimates for Embedded Minimal Surfaces in Terms of T

An interesting problem is to make the characterizations of [Theorem 4.1](#) effective. For instance, to show that a minimal surface with “small” entropy form must be close to a rescaling of a piece of Enneper’s surface. A major challenge is to determine an appropriate notion of smallness for the entropy form – something made more difficult by the need to account for the possible singularities of T . We propose a certain family of quantities as natural ways to measure this smallness and as an application give a novel curvature estimate for embedded minimal surfaces.

Before introducing them we note the following consequence of [Theorem 3.4](#).

Lemma 5.1. *Let Σ be a smooth minimal surface with metric g and entropy form T . For $\alpha > 0$ we define, \hat{T}_α , the α -weighted entropy form of Σ by $\hat{T}_\alpha \equiv 0$ if Σ is flat and by*

$$\hat{T}_\alpha = |K_g|^{\alpha T}$$

otherwise. In either case, the function $|\hat{T}_\alpha|_g^{\frac{1}{1+\alpha}}$ is locally integrable on Σ .

Proof. If Σ is flat then there is nothing to prove as \hat{T}^α is identically zero. Otherwise, by [Theorem 3.4](#), T is smooth away from the isolated poles where K_g has a zero, in particular $|\hat{T}_\alpha|_g^{\frac{1}{1+\alpha}}$ is locally integrable away from the zero set. As Σ is smooth and $K_g \leq 0$, if $K_g(p) = 0$ at a point p , then $\nabla_g K_g(p) = 0$. In particular $K_g = O(r^2)$ where r is the distance to p . On the other hand, by [Theorem 3.4](#), P has a double pole at p and so $|T|_g = Cr^{-2} + o(r^{-2})$ for some constant $C \neq 0$. Hence, $|\hat{T}_\alpha|_g^{\frac{1}{1+\alpha}} = O\left(r^{\frac{2\alpha-2}{1+\alpha}}\right)$. As $\frac{2\alpha-2}{1+\alpha} > -2$ for $\alpha > 0$, $|\hat{T}_\alpha|_g^{\frac{1}{1+\alpha}}$ is integrable in a neighborhood of p . Since p was an arbitrary singularity of T , this proves the lemma. \square

We propose that a reasonable notion of size for the entropy differential T of a smooth minimal surface Σ is given by

$$\|T\|_{\Sigma, \alpha} := 2^{\frac{1}{2(\alpha+1)}} \int_{\Sigma} |\hat{T}_\alpha|_g^{\frac{1}{1+\alpha}} \mu_g = 2^{\frac{1}{2(\alpha+1)}} \int_{\Sigma} |T|_g^{\frac{1}{1+\alpha}} |K_g|^{\frac{\alpha}{1+\alpha}} \mu_g.$$

If $\Sigma_0 \subset \Sigma$, then we obviously have a domain monotonicity property

$$\|T\|_{\Sigma_0, \alpha} \leq \|T\|_{\Sigma, \alpha}.$$

By [Theorem 5.1](#), if Σ is a smooth minimal surface and Σ_0 is pre-compact in Σ , then

$$\|T\|_{\Sigma_0, \alpha} < \infty$$

Finally, if \hat{T}_α^Σ is the α -weighted entropy form of Σ , then $\hat{T}_\alpha^{\lambda\Sigma} = \lambda^{-2\alpha} \hat{T}_\alpha^\Sigma$ is the α -weighted entropy form of $\lambda\Sigma$. To see this observe that T is scale invariant (by construction) and the Gauss curvature scales like λ^{-2} . Hence, as the norm of a (fixed) quadratic differential scales like λ^{-2} ,

$$|\hat{T}_\alpha^{\lambda\Sigma}|_{\lambda g}^{\frac{1}{1+\alpha}} = \lambda^{-2} |\hat{T}_\alpha^\Sigma|_g^{\frac{1}{1+\alpha}} \text{ and so } \|T^{\lambda\Sigma}\|_{\lambda\Sigma, \alpha} = \|T^\Sigma\|_{\Sigma, \alpha}$$

for all $\lambda > 0$. That is, these quantities are scale invariant for all $\alpha > 0$.

Remark 5.2. Clearly, if Σ has an umbilic point, then $\lim_{\alpha \rightarrow 0} \|T\|_{\Sigma, \alpha} = \infty$. Nevertheless, the normalized value $\tau := \lim_{\alpha \rightarrow 0} \alpha \|T\|_{\Sigma, \alpha}$ is finite on reasonable surfaces.

5.1. The Curvature Estimate

We now use the scale invariance of $\|T\|_{\Sigma, \alpha}$ and [Theorem 4.1](#) to prove an ϵ -regularity result:

Theorem 5.3. *There are constants $\epsilon = \epsilon(\alpha) > 0$ and $C = C(\alpha) > 0$ so that: if Σ is a properly embedded minimal surface in B_{2R} and*

$$\|T\|_{\Sigma, \alpha} < \epsilon,$$

then

$$R^2 \sup_{B_R \cap \Sigma} |A|^2 \leq C^2.$$

Remark 5.4. The embeddedness condition is essential as can be seen by considering an appropriate rescaling of Enneper's surface. However, as $\alpha \rightarrow \infty$, $\|T\|_{\Sigma, \alpha} \rightarrow \int_\Sigma |K_g| \mu_g$ the total curvature of Σ . In this case, the above theorem holds *without* the assumption of embeddedness – see White [\[23\]](#) or Anderson [\[2\]](#).

We begin with a Lemma which is crucial to the blow-up argument.

Lemma 5.5. *Fix $C > 0$, $p \in \mathbb{R}^3$ and suppose Σ is a properly embedded smooth surface in $B_{2R}(p) \subset \mathbb{R}^3$ satisfying*

$$\sup_{B_R(p) \cap \Sigma} |A|^2 \geq 16C^2 R^{-2}.$$

Then there is a point $q \in \Sigma$ and scale $s > 0$ so that $B_{Cs}(q) \subset B_{2R}(p)$ and

$$\sup_{B_{Cs}(q) \cap \Sigma} |A|^2 \leq 4s^{-2} = 4|A|^2(q).$$

Proof. With $r(x) = |x - p|$ define the function

$$F(x) = \left(r(x) - \frac{3}{2}R \right)^2 |A|^2.$$

This is a Lipschitz function on $B_{\frac{3}{2}R}(p) \cap \Sigma$ that vanishes on $\partial B_{\frac{3}{2}R}(p) \cap \Sigma$. As F is continuous, non-negative and vanishes on $\partial B_{\frac{3}{2}R}(p) \cap \Sigma$, F achieves its positive maximum at a point $q \in B_{\frac{3}{2}R}(p) \cap \Sigma$.

The lower bound

$$\sup_{B_R(p) \cap \Sigma} |A|^2 \geq 16C^2 R^{-2}$$

implies that $F(q) \geq 4C^2$. Set $s = |A|^{-1}(q)$ and $\sigma = \frac{3}{2}R - r(q)$ and note that $2Cs \leq \sigma$. Furthermore, if $x \in B_{\sigma/2}(q)$, then

$$r(x) \leq \frac{3}{2}R - \frac{\sigma}{2} < \frac{R}{2}$$

and so $\sigma^2 \leq 4(r(x) - \frac{3}{2}R)^2$ and $B_{\sigma/2}(q) \subset B_{\frac{3}{2}R}(p)$. Combining these facts,

$$\sup_{B_{Cs}(q) \cap \Sigma} \frac{\sigma^2}{4} |A|^2 \leq \sup_{B_{\sigma/2}(q) \cap \Sigma} \frac{\sigma^2}{4} |A|^2 \leq \sup_{B_{\sigma/2}(q) \cap \Sigma} F \leq F(q) = \sigma^2 |A|^2(q).$$

Which verifies the claim. \square

We also note the following well-known fact:

Proposition 5.6. *Suppose that $R_i \nearrow \infty$ and that Σ_i are properly embedded minimal surfaces in B_{R_i} so that*

- (1) $0 \in \Sigma_i$ and $|A^{\Sigma_i}|(0) = 1$;
- (2) $\sup_{\Sigma_i} |A^{\Sigma_i}| \leq C < \infty$;

then up to passing to a subsequence, the Σ_i converge smoothly and with multiplicity one to a properly embedded minimal surface Σ in \mathbb{R}^3 so that $0 \in \Sigma$ satisfies $|A^\Sigma|(0) = 1$.

Proof. Up to passing to a subsequence, the Σ_i converge to a smooth minimal lamination \mathcal{L} of \mathbb{R}^3 . As $0 \in \Sigma_i$ for each i , there is a leaf L of the lamination containing 0, moreover $|A^L|(0) = 1$ and so L is not flat. Furthermore, $\sup_\Sigma |A^L| \leq C < \infty$ and so the injectivity radius of L is positive. Hence, by [20], L is properly embedded. Finally, if the convergence is with multiplicity greater than one, then L would be stable and hence flat by [11]. \square

Proof of Theorem 5.3. By rescaling we may take $R = 1$. Assume the theorem is false, then there is a sequence of minimal surfaces Σ_i properly embedded in B_2 so that $\|T^{\Sigma_i}\|_{\Sigma_i, \alpha} \rightarrow 0$ and $\sup_{B_1 \cap \Sigma_i} |A_i^\Sigma|^2 \rightarrow \infty$. By Theorem 5.5, there exist a sequence of $C_i \rightarrow \infty$, points $q_i \in \Sigma_i$ and scales $s_i \rightarrow 0$ so $B_{C_i s_i}(q_i) \subset B_2$ and

$$\sup_{B_{C_i s_i}(q_i) \cap \Sigma_i} |A^{\Sigma_i}|^2 \leq 4s_i^{-2} = 4|A^{\Sigma_i}|^2(q_i).$$

We set $\hat{\Sigma}_i = s_i^{-1}(\Sigma_i \cap B_{C_i s_i}(q_i) - q_i)$. The scaling properties of $\|T\|_{\Sigma, \alpha}$ and domain monotonicity together imply that

$$\|T^{\hat{\Sigma}_i}\|_{\Sigma_i, \alpha} \leq \|T^{\Sigma_i}\|_{\Sigma_i, \alpha} \rightarrow 0.$$

Moreover, each $\hat{\Sigma}_i$ is properly embedded in B_{C_i} , contains 0 and satisfies

$$\sup_{B_{C_i}(0) \cap \hat{\Sigma}_i} |A^{\hat{\Sigma}_i}|^2 \leq 4 = 4|A^{\hat{\Sigma}_i}|^2(0).$$

Hence, by Theorem 5.6, up to passing to a subsequence, the $\hat{\Sigma}_i$ converge to a smooth properly embedded minimal surface $\hat{\Sigma}$ in \mathbb{R}^3 . The convergence is with multiplicity one and $0 \in \hat{\Sigma}$ satisfies $|A^{\hat{\Sigma}}|^2(0) = 1$. By the smoothness

of $\hat{\Sigma}$ and the monotonicity formula, there is a $\rho > 0$ so that in $B_\rho(0) \cap \hat{\Sigma}$ one has $|A^{\hat{\Sigma}}| > \frac{1}{2}$ and so $\pi\rho^2 < \text{Area}(\hat{\Sigma} \cap B_\rho) \leq 2\pi\rho^2$. As the $\hat{\Sigma}_i$ converge smoothly and with multiplicity one to $\hat{\Sigma}$, there is an i_0 large so that $i > i_0$ implies $|A^{\hat{\Sigma}_i}| > \frac{1}{4}$ and $\frac{\pi}{2}\rho^2 < \text{Area}(\hat{\Sigma} \cap B_\rho) \leq 3\pi\rho^2$. As $A^{\Sigma_i} \neq 0$, $\hat{T}_\alpha^{\hat{\Sigma}_i}$ is smooth in $B_\rho \cap \hat{\Sigma}_i$ for $i > i_0$ and converges smoothly to $\hat{T}_\alpha^{\hat{\Sigma}}$ in B_ρ . However, $\|T^{\hat{\Sigma}_i}\|_{B_\rho \cap \hat{\Sigma}_i, \alpha} \rightarrow 0$, hence $\hat{T}_\alpha^{\hat{\Sigma}} \equiv 0$ on $B_\rho \cap \hat{\Sigma}$. Together with $A^{\hat{\Sigma}} \neq 0$ on $B_\rho \cap \hat{\Sigma}$ this implies $T_\alpha^{\hat{\Sigma}} \equiv 0$ on $B_\rho \cap \hat{\Sigma}$ and so $B_\rho \cap \hat{\Sigma}$ is contained in a rescaled Enneper's surface by Theorem [Theorem 4.1](#). It then follows from the strong unique continuation property of smooth minimal surfaces that $\hat{\Sigma}$ is a rescaled Enneper's surface in \mathbb{R}^3 , contradicting that $\hat{\Sigma}$ is properly embedded and proving the theorem. \square

5.2. Gap properties of the entropy form

In light of [Theorem 5.3](#) an interesting question is to determine the optimal constant ϵ in [Theorem 5.3](#). This is equivalent to determining a lower bound for $\|T\|_{\Sigma, \alpha}$ when Σ is a non-flat properly embedded minimal surface in \mathbb{R}^3 . We present some partial results in this direction as well as pose a question about the expected behavior.

A consequence of [Theorem 5.3](#) and [\[19\]](#) is that if $\|T\|_{\Sigma, \alpha}$ is finite on a properly embedded surface, then the surface has finite total curvature.

Proposition 5.7. *If Σ is a properly embedded minimal surface in \mathbb{R}^3 and*

$$\|T\|_{\Sigma, \alpha} < \infty,$$

then

$$\int_{\Sigma} |A|^2 \mu_g = 2 \int_{\Sigma} |K_g| \mu_g < \infty.$$

Proof. Since $\|T\|_{\Sigma, \alpha} < \infty$ there is a value $R > 0$ so that $\|T\|_{\Sigma \setminus \bar{B}_R, \alpha} < \epsilon$ where ϵ is given by [Theorem 5.3](#). This implies that there is a constant $C > 0$ given by [Theorem 5.3](#) so that for $p \in \Sigma \setminus \bar{B}_{2R}$ we have $B_{\frac{1}{2}|p|} p \subset \mathbb{R}^3 \setminus B_R$ and so

$$|A|^2(p) \leq \frac{16C^2}{|p|^2}.$$

That is, Σ has quadratic extrinsic decay of curvature. Hence, by Theorem 1.3 of [\[19\]](#), Σ has finite total curvature. \square

In order to get a more refined result, we first compute:

Lemma 5.8. *If C is the catenoid, then*

$$\|T\|_{C, \alpha} = 2\pi^{3/2} \frac{\Gamma\left(\frac{\alpha}{1+\alpha}\right)}{\Gamma\left(\frac{1}{2} + \frac{\alpha}{1+\alpha}\right)}.$$

Here $\Gamma(x)$ is the Gamma function. Hence,

$$\lim_{\alpha \rightarrow 0} \alpha \|T\|_{C, \alpha} = 2\pi \quad \text{and} \quad \lim_{\alpha \rightarrow \infty} \|T\|_{C, \alpha} = 4\pi.$$

Proof. The Weierstrass data for the catenoid is $(\mathbb{C}/\langle 2\pi i \rangle, J, -e^z, dz)$ where J is the usual complex structure. Using this data and writing $z = x + iy$, we have

$$P = -\frac{1}{2}dz^2, \quad g = \cosh^2 x |dz|^2, \quad K_g = -\frac{1}{\cosh^4 x}.$$

As a consequence, $|T|_g = \frac{\sqrt{2}}{2}|P|_g = \frac{\sqrt{2}}{2\cosh^2 x}$ and so $|\hat{T}_\alpha|_g = \frac{\sqrt{2}}{2\cosh^{2+4\alpha} x}$, hence

$$\|T\|_{C,\alpha} = 2\pi \int_{-\infty}^{\infty} \frac{1}{\cosh^{\frac{2\alpha}{\alpha+1}} x} dx$$

and the integral was evaluated using Mathematica. \square

More generally, we have:

Proposition 5.9. *Let Σ be a non-flat properly immersed minimal surface in \mathbb{R}^3 . If $E \subset \Sigma$ is an embedded end of finite total curvature with branching order $n \geq 0$, then*

$$\lim_{\alpha \rightarrow 0} \alpha \|T\|_{E,\alpha} \geq \frac{(3n+2)(n+2)}{4(n+1)} \pi.$$

If $U \subset \Sigma$ is open and U contains an umbilic point of order $n \geq 1$, then

$$\lim_{\alpha \rightarrow 0} \alpha \|T\|_{U,\alpha} \geq \frac{(3n+4)n}{4(n+1)} \pi.$$

If $\bar{E} \subset \Sigma$ and \bar{E} contains no umbilic points, then we may replace the inequality by an equality. Likewise, if $\bar{U} \subset \Sigma$ and \bar{U} contains only the one umbilic point, then we may replace the inequality by an equality.

Proof. We begin with a general computation. Let $\mathbb{D}^* = \mathbb{D} \setminus \{0\}$ be the punctured disk with the usual complex coordinate $z = re^{i\theta}$. Suppose that Σ is a minimal surface conformally parametrized by \mathbb{D}^* and the following asymptotics hold for the entropy differential, metric and Gauss curvature as $r \rightarrow 0$

$$P = \frac{\beta}{2} \frac{dz^2}{z^2} + O\left(\frac{1}{r^3}\right) dz^2, \quad g = \mu r^k dz \otimes d\bar{z} + O\left(r^{k+1}\right) dz \otimes d\bar{z},$$

and

$$K_g = -\gamma r^l + O\left(r^{l+1}\right),$$

where $\beta \in \mathbb{R}^*$ and $\mu, \gamma, k+l+2 > 0$. As

$$|T_g| = \frac{1}{\sqrt{2}} |P|_g = \frac{|\beta|}{\sqrt{2}\mu} r^{-(k+2)} + O\left(r^{-(k+1)}\right),$$

we compute that

$$\begin{aligned} |\hat{T}_g|^{\frac{1}{1+\alpha}} \sqrt{|g|} &= \left(\frac{|\beta|}{\sqrt{2}\mu} r^{-(k+2)} + O\left(r^{-(k+1)}\right) \right)^{\frac{1}{1+\alpha}} \cdot \left(\gamma r^l + O\left(r^{l+1}\right) \right)^{\frac{\alpha}{1+\alpha}} \\ &\quad \cdot \left(\mu r^k + O\left(r^{k+1}\right) \right) \\ &= 2^{-\frac{1}{2(1+\alpha)}} \mu^{1-\frac{1}{1+\alpha}} |\beta|^{\frac{1}{1+\alpha}} \gamma^{\frac{\alpha}{1+\alpha}} r^{-\frac{1+(k+l+1)\alpha}{1+\alpha}-1} + O\left(r^{-\frac{1+(k+l+1)\alpha}{1+\alpha}}\right). \end{aligned}$$

Picking $R_0 > 0$ so the asymptotic bounds hold for $|z| \leq R_0$, gives

$$\begin{aligned} \|T\|_{\Sigma, \alpha} &\geq 2^{\frac{1}{2(1+\alpha)}} \int_0^{2\pi} \int_0^{R_0} |\hat{T}_g|^{\frac{1}{1+\alpha}} \sqrt{|g|} r dr d\theta \\ &= 2\pi \mu^{1-\frac{1}{1+\alpha}} |\beta|^{\frac{1}{1+\alpha}} \gamma^{\frac{\alpha}{1+\alpha}} \int_0^{R_0} r^{\frac{-1+(k+l+1)\alpha}{1+\alpha}} dr + \int_0^{R_0} O\left(r^{\frac{-1+(k+l+1)\alpha}{1+\alpha}+1}\right) dr \end{aligned}$$

Evaluating the integrals, we conclude that

$$(5.1) \quad \lim_{\alpha \rightarrow 0} \alpha \|T\|_{\Sigma, \alpha} \geq \frac{2\pi|\beta|}{k+l+2}.$$

We can replace inequality by equality provided the bounds hold on all of \mathbb{D}^* .

As E is a non-flat embedded end of finite total curvature and branching order n , it is a catenoidal end if $n = 0$ and a planar end if $n \geq 1$. In either case, up to rotation and homothety, E has Weierstrass data of the form

$$(\mathbb{D}^*, J, z^{n+1}, z^{n-1}(1+zH_0(z)) dz)$$

where (\mathbb{D}^*, J) is the punctured disk and H_0 is a holomorphic function on \mathbb{D} . Writing $z = re^{i\theta}$, we compute that as $r \rightarrow 0$ that

$$\begin{aligned} P &= \left(-\frac{(3n+2)(n+2)}{8z^2} + O\left(\frac{1}{r^3}\right) \right) dz^2 = -\frac{(3n+2)(n+2)}{8} \frac{dz^2}{z^2} + O\left(\frac{1}{r^3}\right) dz^2, \\ g &= \left(\frac{1}{4r^4} + O\left(\frac{1}{r^3}\right) \right) dz \otimes d\bar{z} = \frac{1}{4r^4} (dr^2 + r^2 d\theta^2) + O\left(\frac{1}{r^3}\right) dz \otimes d\bar{z}, \end{aligned}$$

and

$$K_g = -16(n+1)^2 r^{2n+4} + O(r^{2n+5}).$$

Hence, the result follows from (5.1) with $\beta = -\frac{(3n+2)(n+2)}{4}$, $l = 2n+4$ and $k = -4$.

At an umbilic point the computations of Theorem 3.4 imply that we can parameterize a neighborhood of the umbilic point by \mathbb{D} so that as $r \rightarrow 0$

$$P = -\left(\frac{3n^2 + 4n}{8} \right) \frac{dz^2}{z^2} + O(1) dz^2, \quad g = dz \otimes d\bar{z} + O(r) dz \otimes d\bar{z}$$

and

$$K_g = -|a|^2(n+1)^2 r^{2n} + O(r^{2n+1}).$$

Hence, the result follows from (5.1) with $\beta = -\frac{(3n+4)n}{4}$, $l = 2n$ and $k = 0$. \square

From Theorem 5.9 we obtain two corollaries.

Corollary 5.10. *Let Σ be a non-flat properly immersed minimal surface in \mathbb{R}^3 of finite total Gauss curvature with genus g and e embedded ends, then*

$$\lim_{\alpha \rightarrow 0} \alpha \|T\|_{\Sigma, \alpha} = \frac{\pi}{4} \left(8 + 12g + 10(e-2) + \sum_{p \in \mathcal{E} \cup \mathcal{U}} \frac{n(p)}{n(p)+1} \right).$$

Here \mathcal{E} is the set of ends and $n(p) \geq 0$ for $p \in \mathcal{E}$ is the order of branching of the end, i.e., the order of branching of the extension of the Gauss map to p , while \mathcal{U} is the set of umbilic points and $n(p) \geq 1$ is the order of the umbilic point for $p \in \mathcal{U}$.

Proof. As Σ has finite total curvature, a classic result of Osserman [21] implies that Σ is conformal to a compact Riemann surface, M , with a finite number of punctures and that the Gauss map extends meromorphically to M . Let e_1, \dots, e_n denote the punctures which correspond to the ends of Σ , and let u_1, \dots, u_m denote the umbilic points. Pick U_1, \dots, U_{n+m} disjoint open subsets of M each containing either an e_i or a u_j . We may naturally think of the U_i as open subsets of Σ . Notice that $\Sigma_0 = \Sigma \setminus \bigcup_{i=1}^{n+m} U_i$ is compact and contains no umbilic points and so there is a $C > 0$ so that for all α , $\|T\|_{\Sigma_0, \alpha} \leq C$. Hence,

$$\lim_{\alpha \rightarrow 0} \alpha \|T\|_{\Sigma, \alpha} = \sum_{i=1}^{n+m} \lim_{\alpha \rightarrow 0} \alpha \|T\|_{U_i, \alpha}.$$

As each U_i is either an embedded end containing no umbilic points or contains exactly one umbilic point, Theorem 5.9 gives that

(5.2)

$$\lim_{\alpha \rightarrow 0} \alpha \|T\|_{\Sigma, \alpha} = \frac{\pi}{4} \left(\sum_{p \in \mathcal{E}} \frac{(3n(p) + 2)(n(p) + 2)}{n(p) + 1} + \sum_{p \in \mathcal{U}} \frac{(3n(p) + 4)n(p)}{n(p) + 1} \right).$$

The Poincaré-Hopf index theorem applied to the Hopf differential Q implies that

$$4g - 4 = \sum_{p \in \mathcal{E}} (n(p) - 2) + \sum_{p \in \mathcal{U}} n(p).$$

The proof is concluded by applying this identity to (5.2). □

Corollary 5.11. *If Σ is a non-flat properly embedded minimal surface in \mathbb{R}^3 , then*

$$\lim_{\alpha \rightarrow 0} \alpha \|T\|_{\Sigma, \alpha} \geq 2\pi,$$

with equality if and only if Σ is a catenoid.

Proof. If $\lim_{\alpha \rightarrow 0} \alpha \|T\|_{\Sigma, \alpha} = \infty$, then there is nothing to show. If this limit is finite, then Proposition Theorem 5.7 implies that Σ has finite total curvature. By the strong half-space theorem [16] and the classification of embedded ends, as Σ is not plane it must have at least two (catenoidal) ends. Hence, by Theorem 5.10,

$$\lim_{\alpha \rightarrow 0} \alpha \|T\|_{\Sigma, \alpha} \geq 2\pi$$

with equality if and only if Σ has genus zero, no other ends and no umbilic points. Hence, the Gauss map extends to an unbranched cover of the sphere, and so Σ is the catenoid. □

We pose the following question:

Question 5.12. *Let Σ be a non-flat properly embedded minimal surface in \mathbb{R}^3 and let C be the catenoid. Is it true that for finite α*

$$\|T^\Sigma\|_{\Sigma, \alpha} \geq \|T^C\|_{C, \alpha}$$

with equality only if Σ is a catenoid? This is true in the limit as $\alpha \rightarrow 0$ and $\alpha \rightarrow \infty$.

5.3. Compactness properties for uniform bounds on T

We conclude with a compactness result for sequences of properly embedded minimal surfaces Σ_i which admit a uniform bound on the entropy differential. This is a standard consequence of [Theorem 5.3](#) and the removable singularities result of [\[19\]](#).

Theorem 5.13. *Fix $\alpha > 0$ and suppose that Σ_i is a sequence of properly embedded minimal surfaces in an open region $\Omega \subset \mathbb{R}^3$ with entropy forms T^{Σ_i} satisfying*

$$\|T^{\Sigma_i}\|_{\Sigma_i, \alpha} \leq \bar{C} < \infty.$$

Then there is a subsequence of the Σ_i and a finite (possibly empty) set of points $p_1, \dots, p_N \in \Omega$ so that:

- (1) *On each compact set $K \subset \subset \Omega \setminus \{p_1, \dots, p_N\}$,*

$$\sup_{K \cap \Sigma_i} |A| \leq C(K) < \infty;$$

- (2) *$\epsilon N < 2\bar{C}$ where $\epsilon = \epsilon(\alpha) > 0$ is given by [Theorem 5.3](#);*

- (3) *The Σ_i converge in $\Omega \setminus \{p_1, \dots, p_N\}$ to a smooth minimal lamination \mathcal{L} of $\Omega \setminus \{p_1, \dots, p_N\}$. Moreover, the closure of $\bar{\mathcal{L}}$ of \mathcal{L} in Ω is a smooth lamination of Ω .*

Proof. We define a sequence of Radon measures, $\mu_{i, \alpha}$, on Ω by setting

$$\mu_{i, \alpha}(U) = 2^{\frac{1}{2(\alpha+1)}} \int_{\Sigma_i \cap U} |\hat{T}_\alpha^{\Sigma_i}|^{\frac{1}{\alpha+1}} \mu_g$$

so

$$\mu_{i, \alpha}(\Omega) = \|T_\alpha^{\Sigma_i}\|_{\Sigma_i, \alpha} \leq \bar{C} < \infty.$$

By the standard compactness theorem for Radon measures, up to passing to a subsequence, the $\mu_{i, \alpha}$ weak* converge to a Radon measure μ . It follows with [Theorem 5.3](#) that if for $p \in \Omega$ there is an $r > 0$ so that $B_{2r}(p) \subset \Omega$ and $\mu(B_{2r}(p)) < \frac{1}{2}\epsilon$, then there is a constant $C > 0$ so that

$$\sup_{B_r(p) \cap \Sigma_i} |A|^2 \leq \frac{C^2}{r^2} < \infty.$$

By standard covering arguments and the pigeonhole principle one concludes that there are at most N points $p_1, \dots, p_N \in \Omega$ with $N\epsilon < 2\bar{C}$ so that no such r exists. It follows that for any compact set $K \subset \Omega \setminus \{p_1, \dots, p_N\}$ we have the curvature estimate:

$$\sup_{K \cap \Sigma_i} |A| \leq C(K) < \infty.$$

This verifies Items (1) and (2).

To prove Item (3), we note that the uniform curvature estimates of Item (2) and standard compactness results – see Appendix B of [\[10\]](#) – imply that, up to passing to a further subsequence, the Σ_i converge in $\Omega \setminus \{p_1, \dots, p_N\}$ to a smooth minimal lamination, \mathcal{L} , of $\Omega \setminus \{p_1, \dots, p_N\}$. We claim that near each p_i the lamination has quadratic curvature decay. To prove this we apply

the Lebesgue decomposition theorem to μ and to L_Ω , Lebesgue measure on \mathbb{R}^3 restricted to Ω . This implies

$$\mu = \mu_{reg} + \mu_{sing}.$$

where μ_{reg} is absolutely continuous with respect to L_Ω while $\mu_{sing} \perp L_\Omega$. In fact, the support of μ_{sing} is $\{p_1, \dots, p_n\}$, because \mathcal{L} is a lamination of $\Omega \setminus \{p_1, \dots, p_n\}$. Hence,

$$\lim_{\rho \rightarrow 0} \mu(B_\rho(p_i) \setminus \{p_i\}) = \lim_{\rho \rightarrow 0} \mu_{reg}(B_\rho(p_i) \setminus \{p_i\}) = 0$$

and so there is a $\delta > 0$ so that $\mu(B_{2\delta}(p_i) \setminus \{p_i\}) < \epsilon$. Hence, for $p \in B_\delta(p_i) \setminus \{p_i\}$ we may apply [Theorem 5.3](#) to the points $q_j \in \Sigma_j$ with $q_j \rightarrow p$ and use the smooth convergence to conclude that

$$|A|^2(p) \leq \frac{4C^2}{|p - p_i|^2}.$$

Theorem 1.2 of [\[19\]](#) then implies that each p_i is a removable singularity of \mathcal{L} which concludes the proof of Item (3). \square

Appendix A. Ricci Solitons

We remark on an interesting connection the entropy form makes between minimal surfaces and two-dimensional Ricci solitons. Recall, a smooth one-parameter family of metrics g_t on a fixed manifold M is a *Ricci flow* provided

$$\frac{d}{dt}g_t = -2\text{Ric}_{g_t}.$$

This flow was introduced by Hamilton in [\[13\]](#). When M is a surface this simplifies to

$$\frac{d}{dt}g_t = -2K_{g_t}g_t.$$

We say (M, g) is a *Ricci soliton* provided there is a vector field X on M and a constant λ so that

$$-2\text{Ric}_g = L_X g - 2\lambda g.$$

For such a g the family $g_t = (1 - 2\lambda t)\phi_t^*g$ is a Ricci flow – here ϕ_t is the flow of X . When $\lambda = 0$ the soliton is steady (i.e. of unchanging geometry) while when $\lambda > 0$ it is shrinking and when $\lambda < 0$ it is expanding. If $X = {}^g\nabla f$ then we say g is a *gradient Ricci soliton* and f is a *soliton potential*. For such gradient Ricci solitons

$$L_X g = 2{}^g\nabla^2 f.$$

So g is a gradient Ricci soliton provided

$${}^g\nabla^2 f + \text{Ric}_g - \lambda g = 0.$$

If M is a surface this implies

$${}^g\nabla^2 f + K_g g - \lambda g = 0$$

which is equivalent to

$$\Delta_g f = 2(\lambda - K_g) \quad \text{and} \quad {}^g\dot{\nabla}^2 f = 0.$$

Covariant differentiation of the last equation gives (in coordinates)

$${}^g\nabla_j {}^g\nabla_k (\partial_i f) = \frac{1}{2} (\partial_k \Delta_g f) g_{ij}.$$

Using the identity ${}^g\nabla_j {}^g\nabla_k (\partial_i f) - {}^g\nabla_k {}^g\nabla_j (\partial_i f) = R_{ijk}^l \partial_l f$, where R_{ijk}^l are the components of the curvature tensor of g , we obtain

$$\left(\frac{1}{2} \partial_k \Delta_g f + K \partial_k f \right) g_{ij} = \left(\frac{1}{2} \partial_j \Delta_g f + K \partial_j f \right) g_{ik}.$$

Contracting with g^{ij} implies

$$0 = K df + \frac{1}{2} d\Delta_g f = K df - dK.$$

Hence near a point p where $K_g \neq 0$ we have

$$df = d \log |K_g|$$

and so

$${}^g\nabla^2 \log |K_g| = {}^g\nabla^2 f = (\lambda - K_g)g.$$

From this we see that

$$\Delta_g \log |K_g| = 2(\lambda - K_g) \quad \text{and} \quad \mathring{\nabla}_g^2 \log |K_g| = 0.$$

The converse is also true:

Proposition A.1. *Let (M, g) be a (possibly open) Riemannian surface with $K_g \neq 0$. It is a gradient Ricci soliton if and only if*

$$\mathring{\nabla}_g^2 \log |K_g| = 0 \quad \text{and} \quad \Delta_g \log |K_g| = 2(\lambda - K_g)$$

for some $\lambda \in \mathbb{R}$. Moreover, if (M, g) is a gradient Ricci soliton, then it has soliton potential $\log |K_g|$. The sign of λ depends on whether the soliton is expanding, steady or shrinking.

Recall that if (M, g) is a Riemannian surface with $K_g < 0$ and g satisfies the Ricci condition (2.1), then $\hat{g} = |K_g|^{3/4} g$ satisfies $K_{\hat{g}} > 0$ and $\Delta_{\hat{g}} \log K_{\hat{g}} = -2K_{\hat{g}}$. Hence, a consequence of Theorem 4.1 and a straightforward computation is:

Corollary A.2. *The metric of Enneper's surface g_{enn} corresponds to the cigar soliton metric g_{cig} under the map $g \rightarrow |K_g|^{3/4} g$. Furthermore, homotheties of g_{enn} are the only minimal surface metrics which correspond to gradient Ricci soliton metrics in this manner.*

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